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Serial Number: 10/671,329

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 **PALM INTRANET**

Inventor Information for 10/671329

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US 20060071622 A1	US- PGPUB	20060406	31	Ultra-compact, high- performance motor controller and method of using same	318/254		Townsend; William T. et al.
US 20050130588 A1	US- PGPUB	20050616		Delay based space and time coordinated repeater system	455/11.1		Pratt, Gill et al.
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US 20050070834 A1	US- PGPUB	20050331		Active Ankle Foot Orthosis	602/28		Herr, Hugh et al.
US 20040255140 A1	US- PGPUB	20041216		Data repository and method for promoting network storage of data	713/193	707/200; 726/29	Margolus, Norman H. et al.
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US 20040064195 A1	US- PGPUB	20040401		Variable- mechanical- impedance artificial legs	623/24	602/23; 623/26; 623/35; 623/44; 623/46; 623/52; 623/55	Herr, Hugh
US 20040039454 A1	US- PGPUB	20040226		Speed-adaptive and patient- adaptive prosthetic knee	623/39	623/44	Herr, Hugh M. et al.
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				prosthetic knee			
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US 20010029400 A1	US- PGPUB	20011011		Electronically controlled prosthetic knee	623/24	623/43	Deffenbaugh, Bruce W. et al.
US 6764520 B2	USPAT	20040720		Electronically controlled prosthetic knee	623/24	623/26; 623/39	Deffenbaugh; Bruce W. et al.
US 6610101 B2	USPAT	20030826		Speed-adaptive and patient- adaptive prosthetic knee	623/24	623/44	Herr; Hugh M. et al.
US 6494039 B2	USPAT	20021217		Force- controlled hydro-elastic actuator	60/368	60/393; 60/434; 92/84	Pratt; Gill A. et al.
US 6029374 A	USPAT	20000229		Shoe and foot prosthesis with bending beam spring structures	36/27	36/151; 36/158; 36/168; 36/179; 36/38; 36/7.8; 36/92; 623/55	Herr; Hugh M. et al.
US 5910720 A	USPAT	19990608		Cross-shaped torsional spring	318/623	318/630; 318/632	Williamson; Matthew M. et al.
US 5808427 A	USPAT	19980915		Vehicle drive control system	318/139	180/65.1; 318/10; 318/446; 318/587	Worden; James D. et al.
US 5701686 A	USPAT	19971230		Shoe and foot prosthesis with bending beam spring structures	36/27	36/7.8	Herr; Hugh M. et al.
US 5691885 A	USPAT	19971125		Three- dimensional	361/735	361/729; 361/730;	Ward; Stephen A. et

				interconnect having modules with vertical top and bottom connectors		361/733; 439/44	al.
US 5650704 A	USPAT	19970722		Elastic actuator for precise force control	318/623	318/560; 318/630; 318/632	Pratt; Gill A. et al.
US 5637971 A	USPAT	19970610		Suppression of multiple noise-related signals in pulse width modulated signals	318/599	318/138; 318/254; 318/280; 318/439	Pratt; Gill A.
US 5634041 A	USPAT	19970527		Rationally clocked communication interface	713/375		Pratt; Gill A. et al.
US 5568361 A	USPAT	19961022		Three-dimensional electronic circuit of interconnected modules	361/735	361/729; 361/784; 361/785; 361/790; 361/803; 439/74	Ward; Stephen A. et al.
US 5458143 A	USPAT	19951017		Crutch with elbow and shank springs	135/68	135/71	Herr; Hugh M.
US 5367790 A	USPAT	19941129		Shoe and foot prosthesis with a coupled spring system	36/27	36/7.8; 623/55	Gamow; Rustem I. et al.
US 5228138 A	USPAT	19930713	16	Synchronization of hardware oscillators in a mesh-connected parallel processor	713/401		Pratt; Gill A. et al.
US 4923475 A	USPAT	19900508		Inflatable limb prosthesis with preformed inner surface	623/37		Gosthonian; Barry M. et al.